

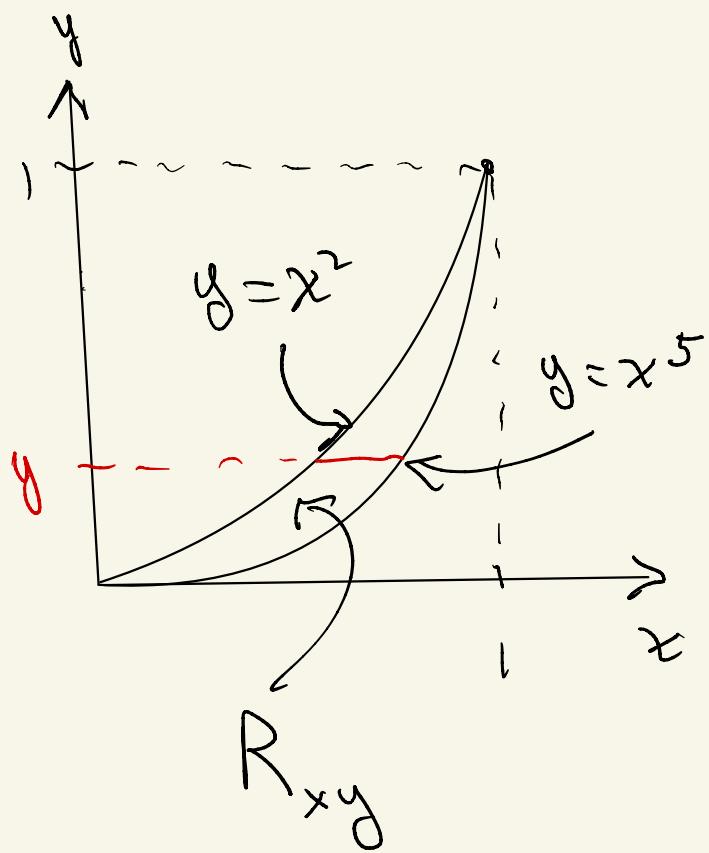
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Math 21D Midterm I Solutions

Winter 2023

#1

(a) $\int_0^1 \int_{x^5}^{x^2} dy dx$



b)

$$\int_0^1 \int_{y^5}^{y^2} dx dy$$

(2)

$$\textcircled{#2} \quad \textcircled{a} \quad \bar{x} = \frac{M_y}{M} \quad \bar{y} = \frac{M_x}{M}$$

$$M = \iint_{R_{xy}} s \, dA = \int_0^1 \int_{x^5}^{x^2} x^2 y^3 \, dy \, dx$$

$$M_y = \iint_{R_{xy}} x \, dA = \int_0^1 \int_{x^5}^{x^2} x^3 y^3 \, dy \, dx$$

$$M_x = \iint_{R_{xy}} y \, dA = \int_0^1 \int_{x^5}^{x^2} x^2 y^4 \, dy \, dx$$

$$\textcircled{b} \quad K_E = \frac{1}{2} I_{y=1} \omega^2$$

$$I_{y=1} = \iint_{R_{xy}} (x-1)^2 s \, dA = \int_0^1 \int_{x^5}^{x^2} (x-1)^2 x^2 y^3 \, dy \, dx$$

#3

a)

$$x = r \cos \theta \quad y = r \sin \theta$$

(3)

$$J = \det \begin{vmatrix} \frac{\partial(x,y)}{\partial(r,\theta)} \end{vmatrix} = \begin{vmatrix} \cos \theta & -r \sin \theta \\ \sin \theta & r \cos \theta \end{vmatrix}$$

$$= r \cos^2 \theta + r \sin^2 \theta = r \quad \checkmark$$

b) Since $\det \begin{vmatrix} \frac{\partial(x,y)}{\partial(u,\theta)} \end{vmatrix} > 0$, then

(r, θ) is positively oriented wrt (x,y)

$$\text{But } \det \begin{vmatrix} \frac{\partial(x,y)}{\partial(\theta,r)} \end{vmatrix} = \begin{vmatrix} x_\theta & x_r \\ x_\theta & x_r \end{vmatrix}$$

$$= \begin{vmatrix} -r \sin \theta & \cos \theta \\ r \cos \theta & \sin \theta \end{vmatrix} = -r$$

so (θ, r) is negatively oriented wrt (x,y)

(4)

#4

$$f(x, y, z) = \frac{1}{r^2} = r^{-2}$$

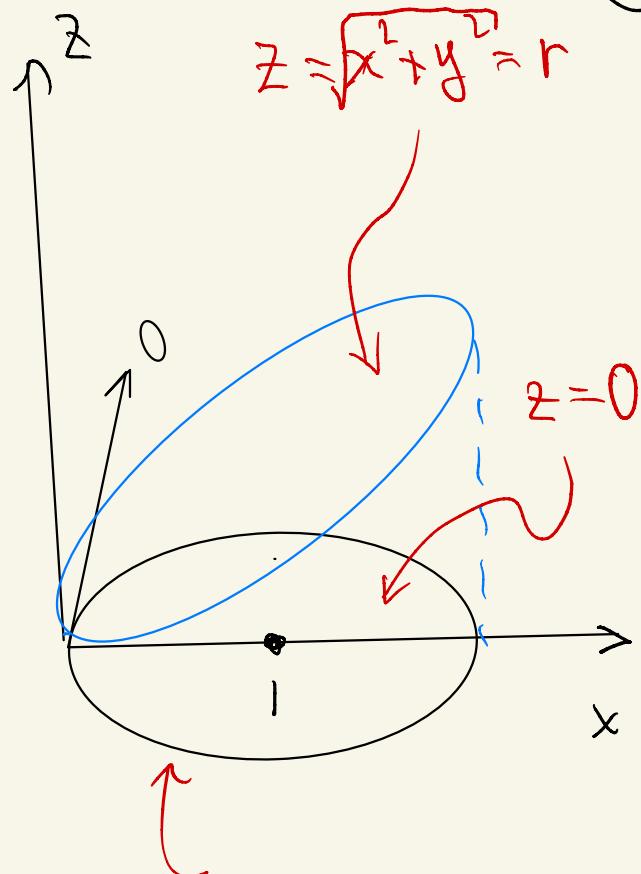
$$I = \int_{-\pi/2}^{\pi/2} \int_0^{2\cos\theta} \int_0^r r^2 r dz dr d\theta$$

$$= \int_{-\pi/2}^{\pi/2} \int_0^{2\cos\theta} r^{-1} z \Big|_0^r dr d\theta$$

$$= \int_{-\pi/2}^{\pi/2} \int_0^{2\cos\theta} r^{-1} \cdot r dr d\theta$$

$$= \int_{-\pi/2}^{\pi/2} 2 \cos\theta d\theta$$

$$= 2 \sin\theta \Big|_{-\pi/2}^{\pi/2} = 2(1 - (-1)) = 2 \cdot 2 = 4$$



$$(x-1)^2 + y^2 = 1$$

$$x^2 - 2x + 1 + y^2 = 1$$

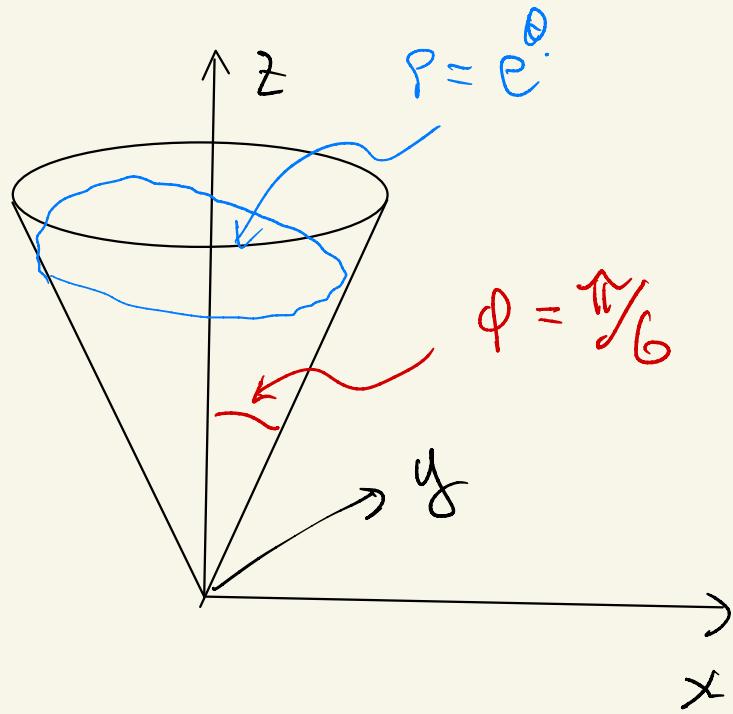
$$r^2 = 2x = 2r \cos\theta$$

$$\boxed{r = 2 \cos\theta}$$

#5

@

(5)



$$I = \int_0^{2\pi} \int_0^{\pi/6} \int_0^{\rho} \rho^2 \sin^2 \phi \, d\rho \, d\phi \, d\theta$$

$$\textcircled{b} \quad S = \frac{1}{\sin^2 \theta} \quad \text{so Mass } M \text{ in kg is } \textcircled{6}$$

$$M = \int_0^{2\pi} \int_0^{\pi/6} \int_0^{\theta} S^2 dS d\varphi d\theta$$

$$\left. S^3 \right|_0^{\theta} = \frac{e^{3\theta} - 1}{3}$$

$$= \int_0^{2\pi} \int_0^{\pi/6} \frac{e^{3\theta} - 1}{3} d\varphi d\theta = \frac{\pi}{6} \int_0^{2\pi} \frac{e^{3\theta} - 1}{3} d\theta$$

$$= \frac{\pi}{6} \left[\frac{\frac{1}{3} e^{3\theta} - \theta}{3} \right]_0^{2\pi} = \frac{\pi}{6} \left(\frac{1}{9} e^{6\pi} - \frac{2\pi + 1}{3} \right)$$

in kg